

Figure 1

## Coordination Interfaces

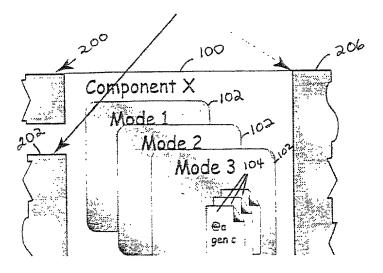


Figure 2

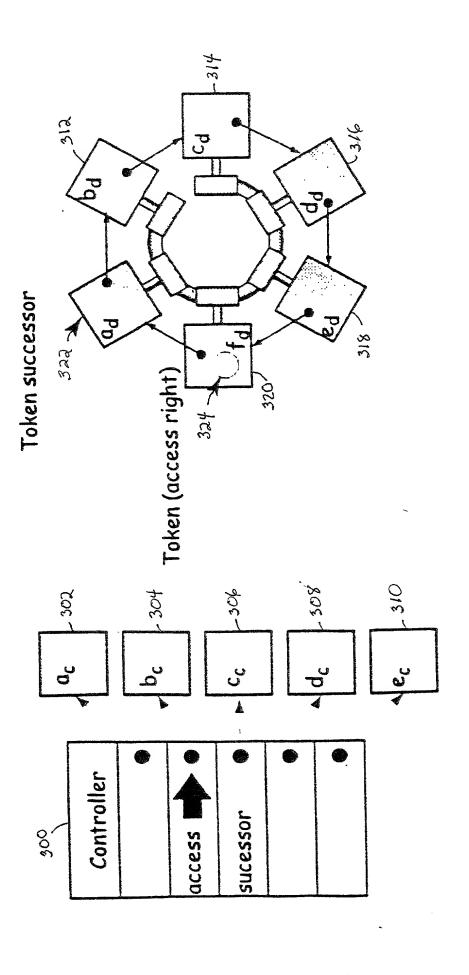


Figure 3A

Figure 3B

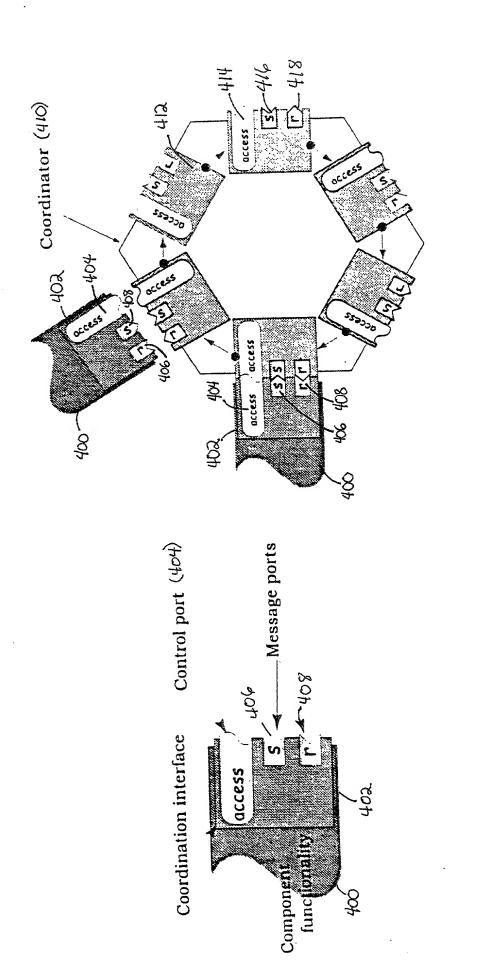


Figure 4A

Figure 4B

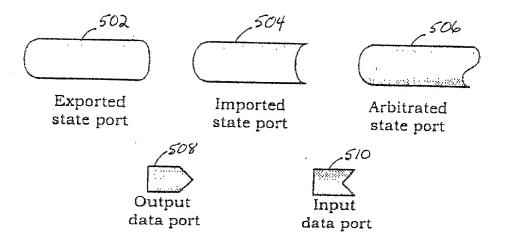
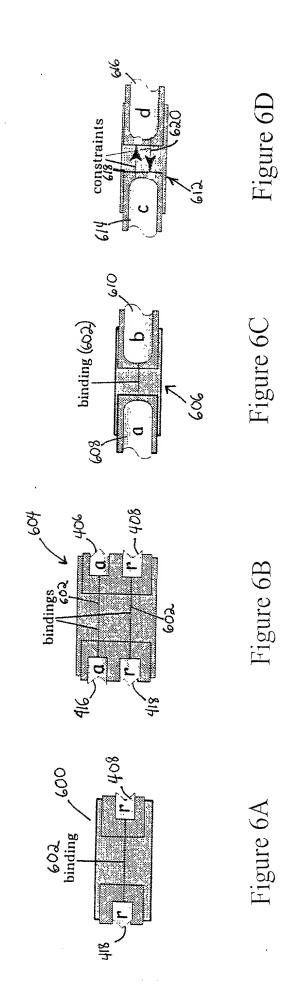


Figure 5



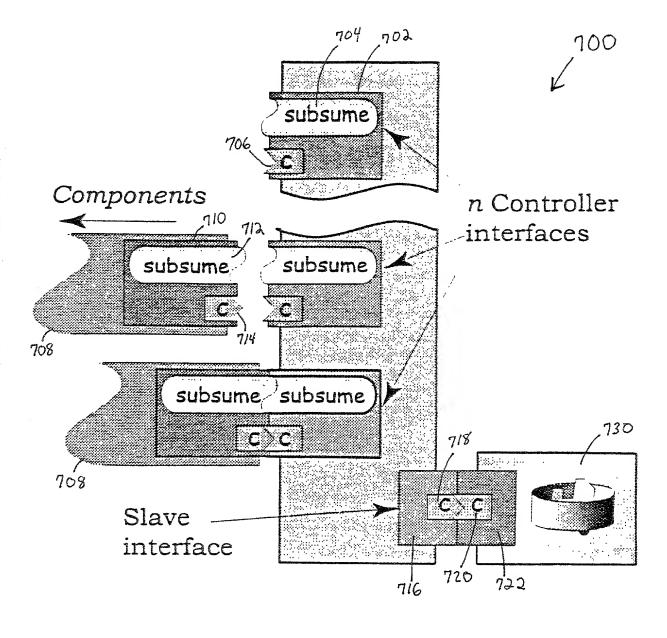


Figure 7

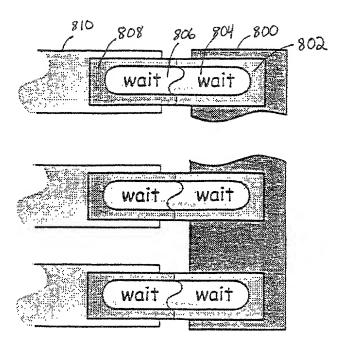


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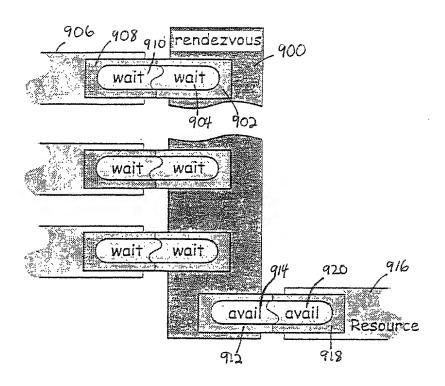


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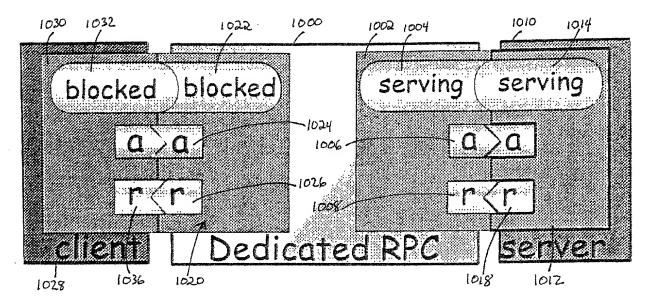
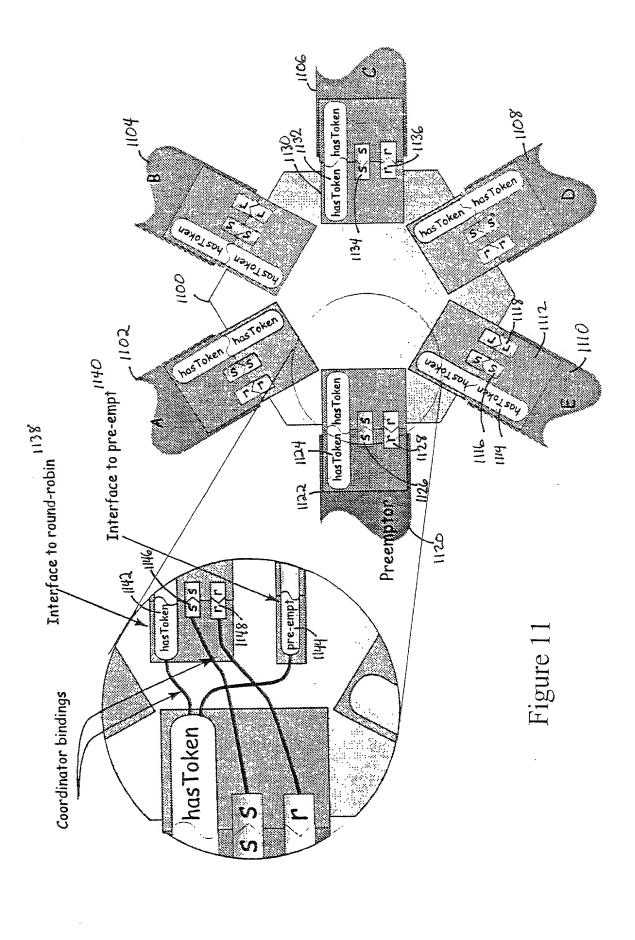
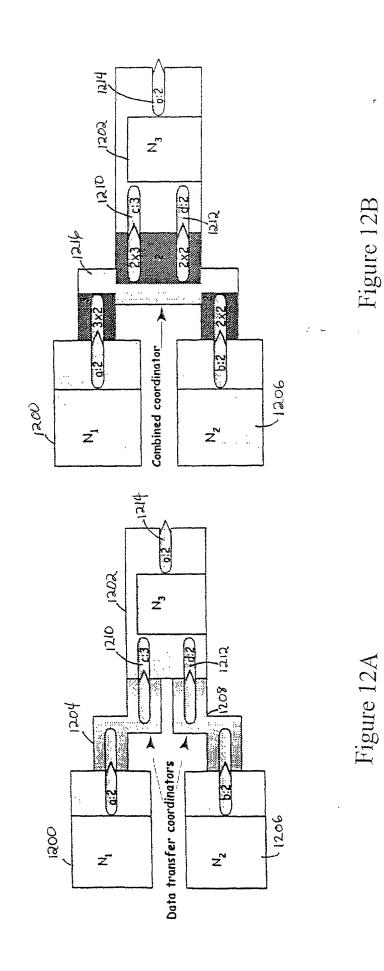


Figure 10





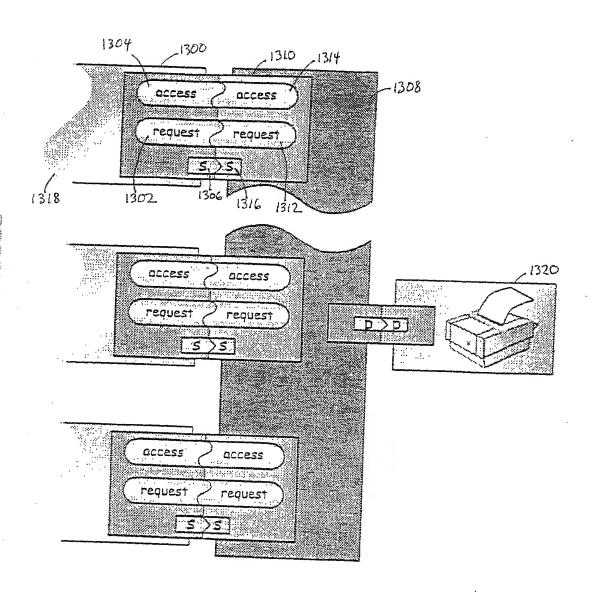


Figure 13

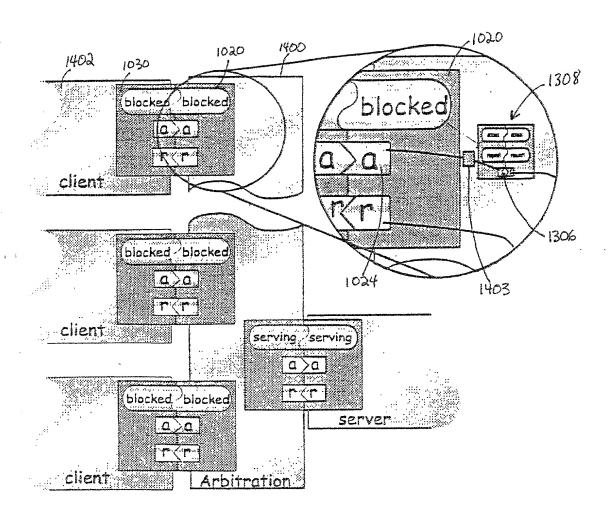


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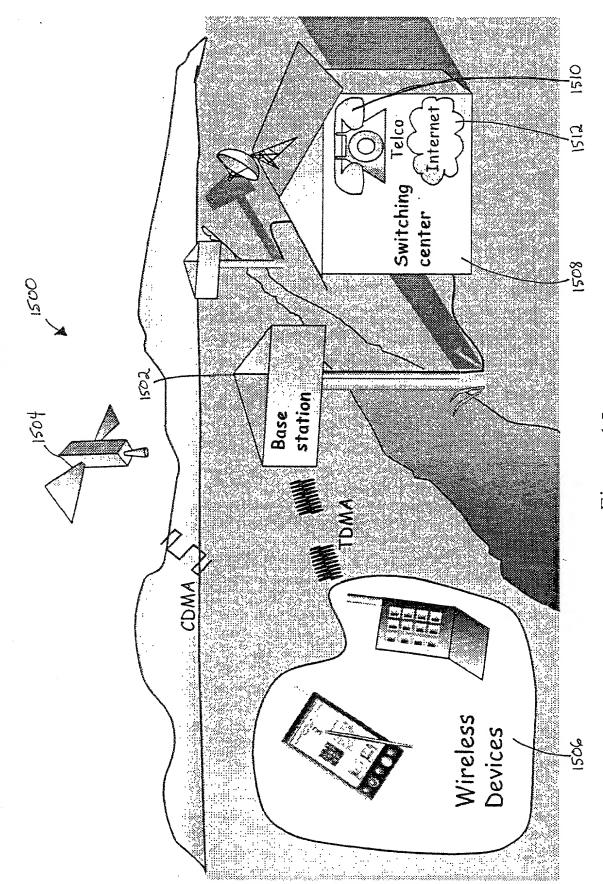


Figure 15

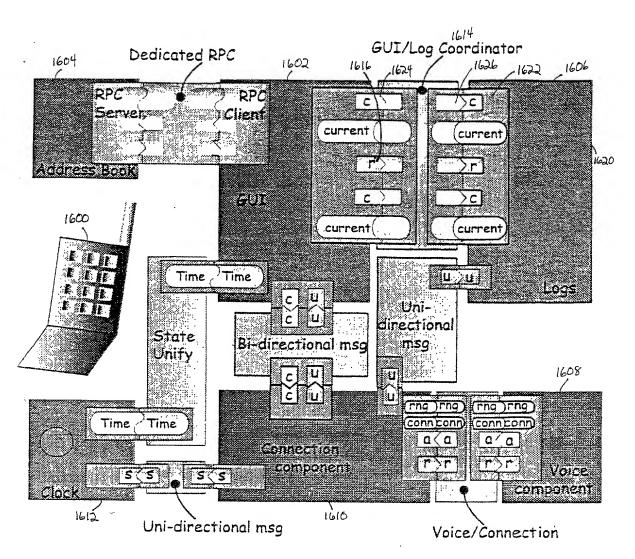


Figure 16

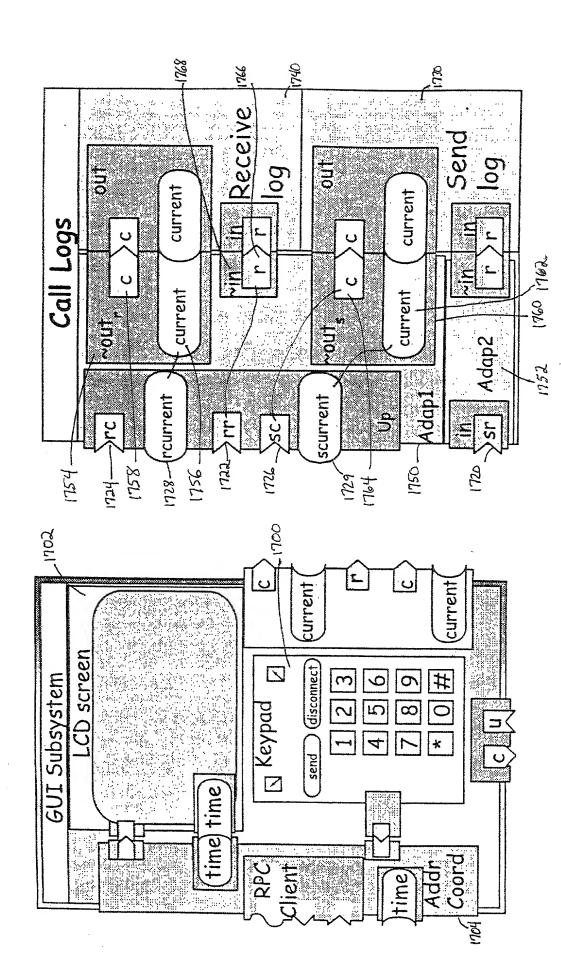


Figure 17A

Figure 17B

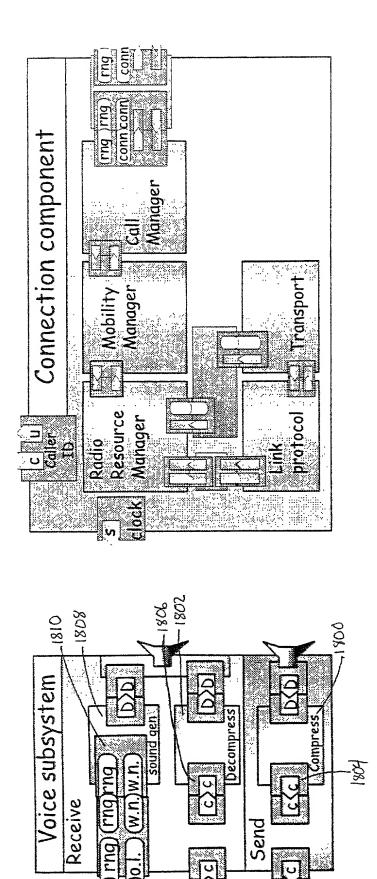


Figure 18A

Figure 18B

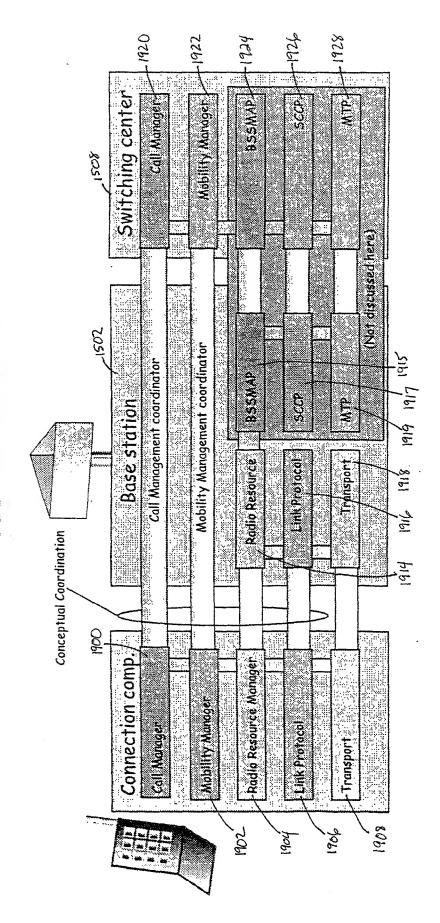


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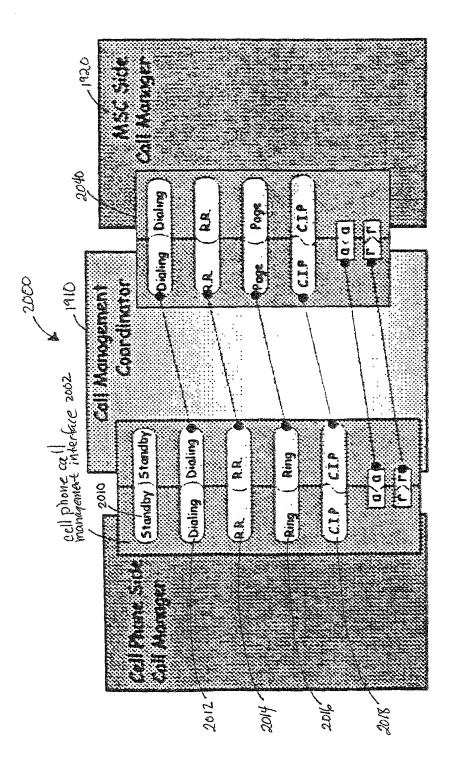


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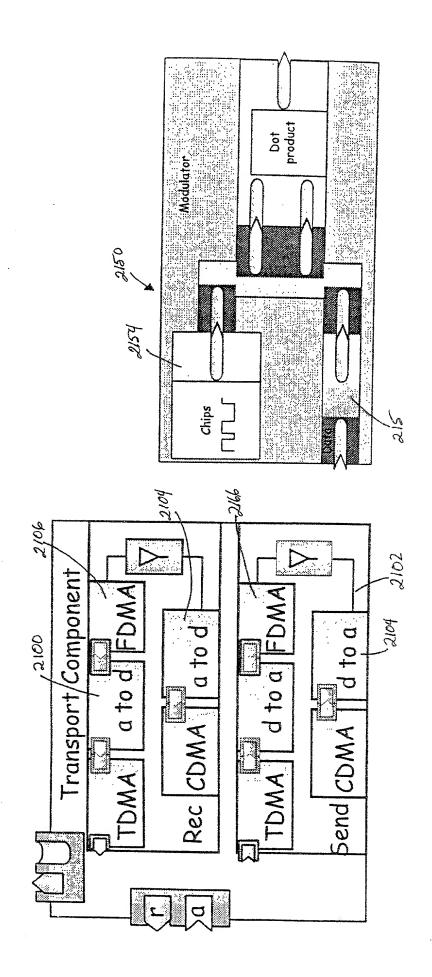


Figure 21A

Figure 21B

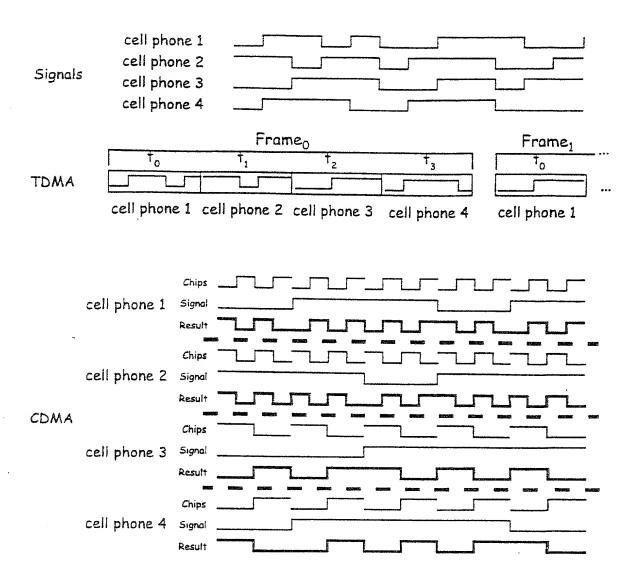


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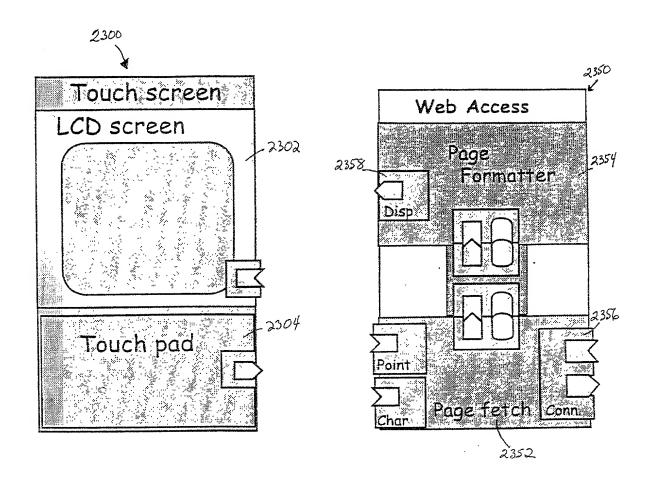


Figure 23A

Figure 23B

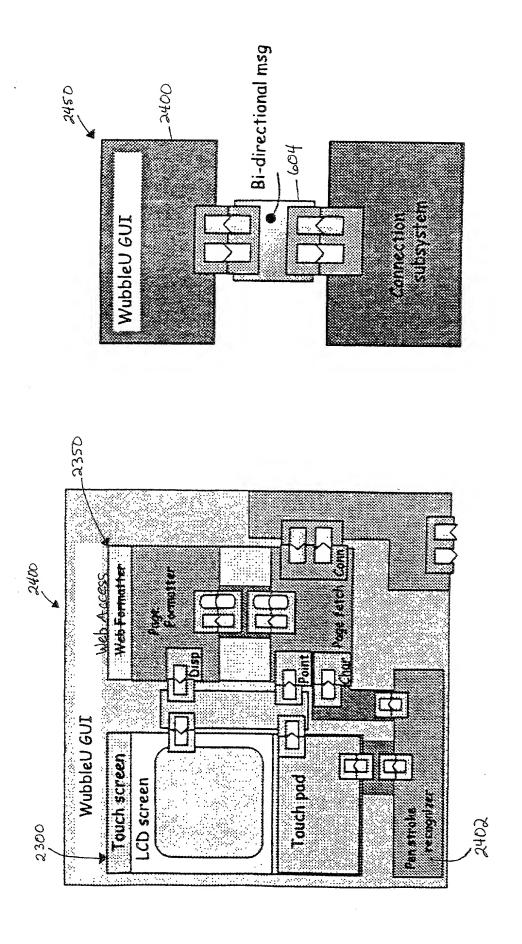
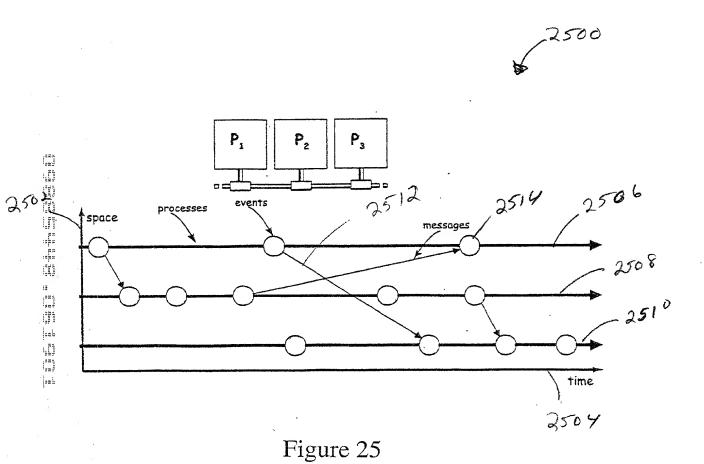


Figure 24B

Figure 24A



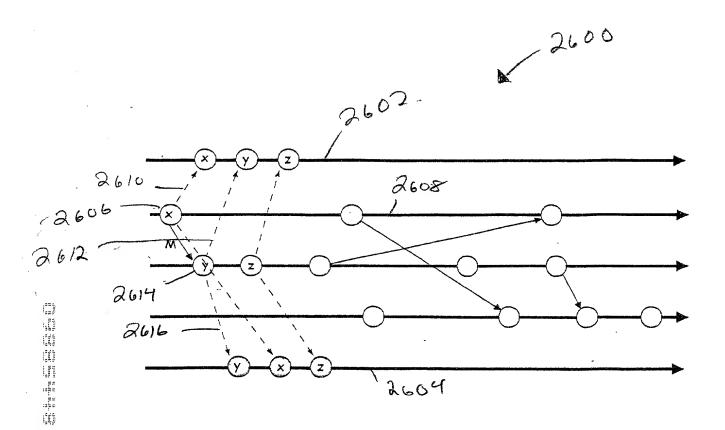


Figure 26

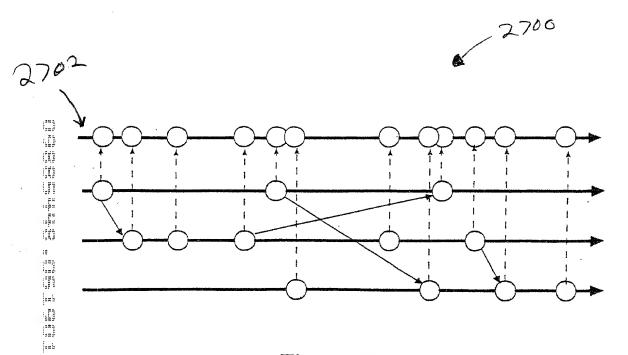


Figure 27

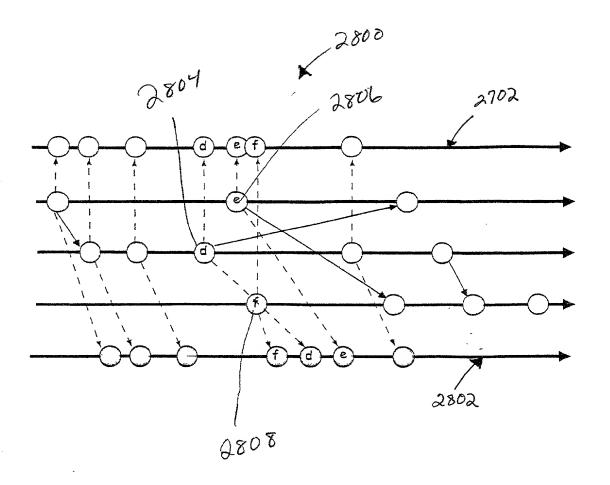


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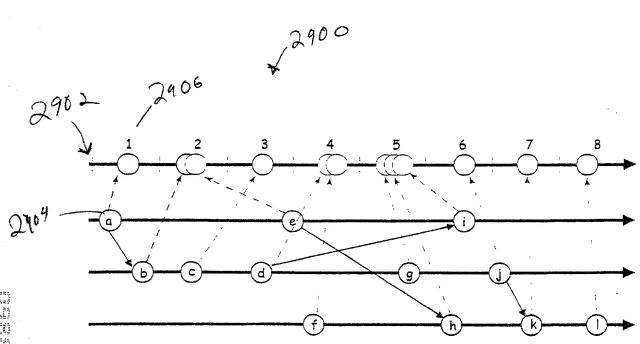


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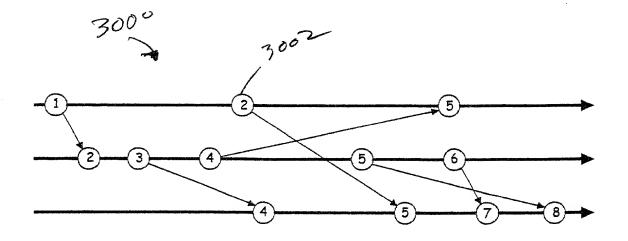


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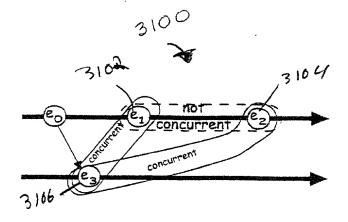


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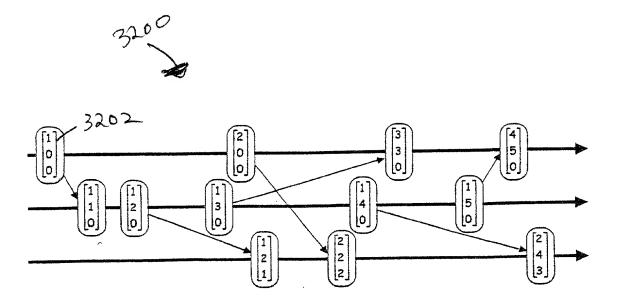


Figure 32



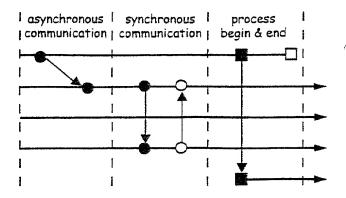


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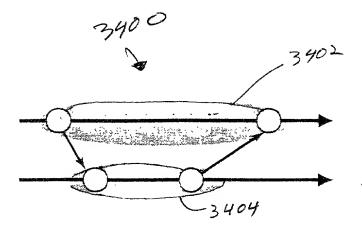


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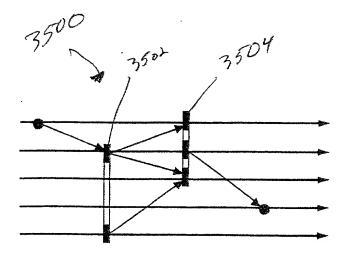


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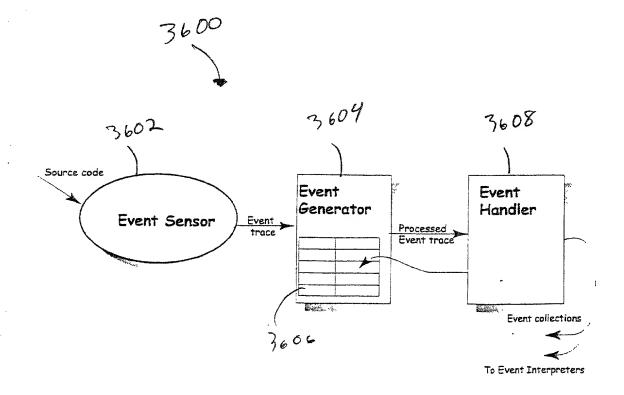


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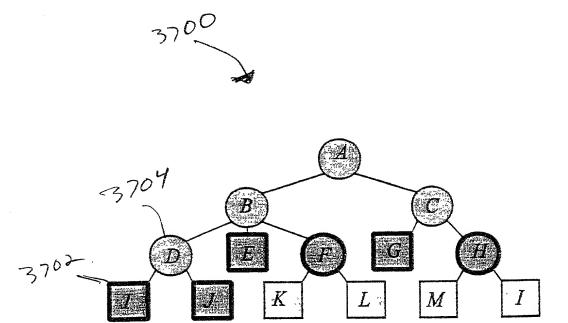
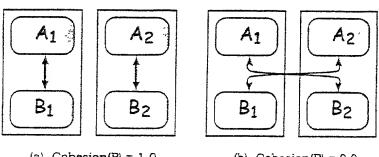
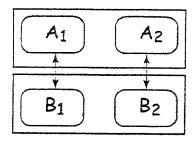


Figure 37



(a) Cohesion(P) = 1.0 Coupling(P) = 0.5

(b) Cohesion(P) = 0.0 Coupling(P) = 1.0



(c) Cohesion(P) = 1.0 Coupling(P) = 0.5

Figure 38

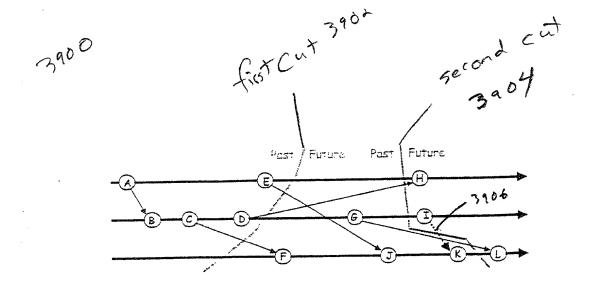


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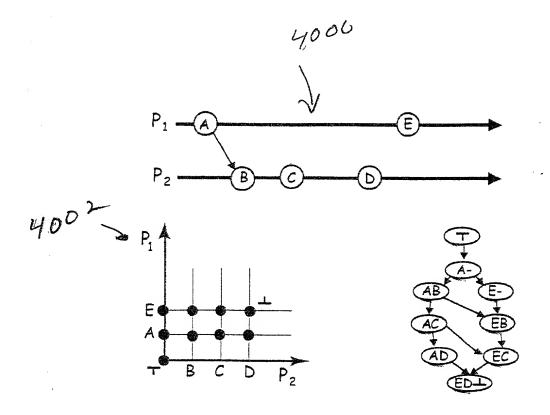


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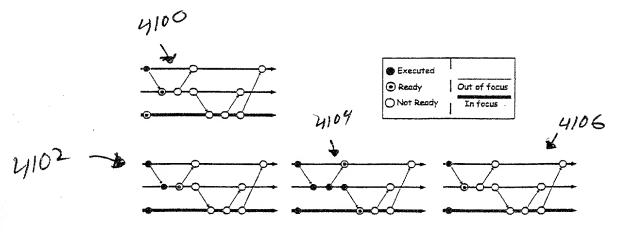


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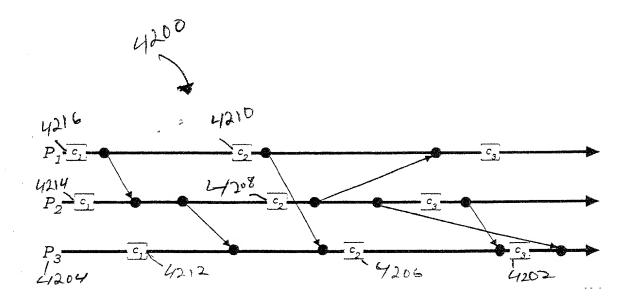
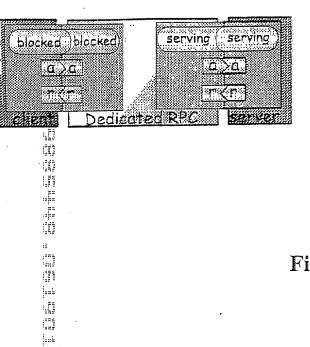


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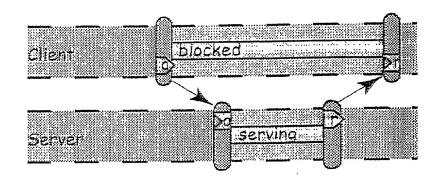


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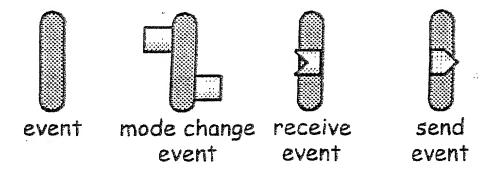


Figure 44

A	Simple control state
X:18	Variable value
X > 7	General control state

Figure 45

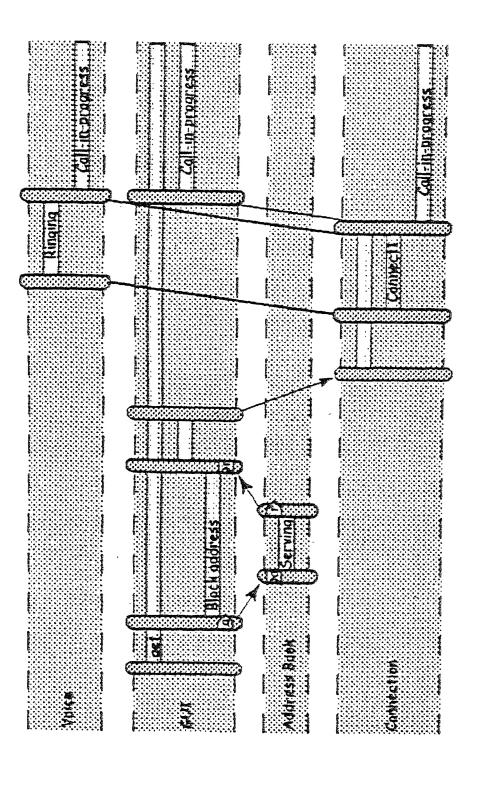


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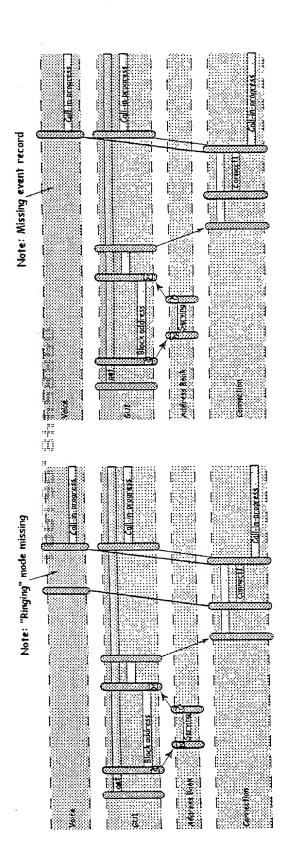


Figure 47A

Figure 47B

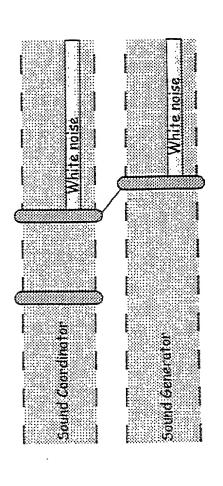


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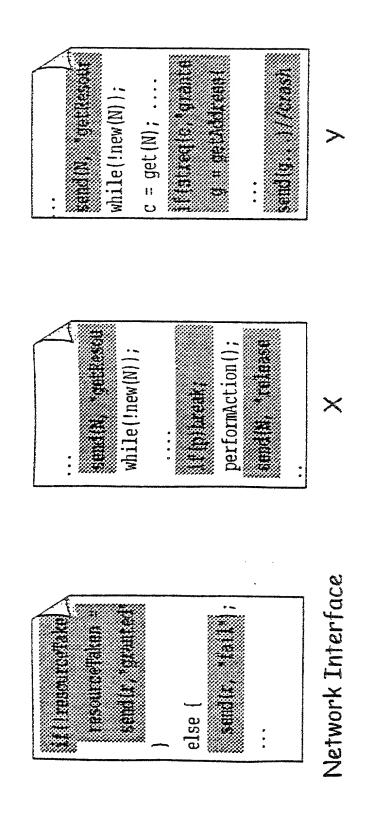


Figure 49

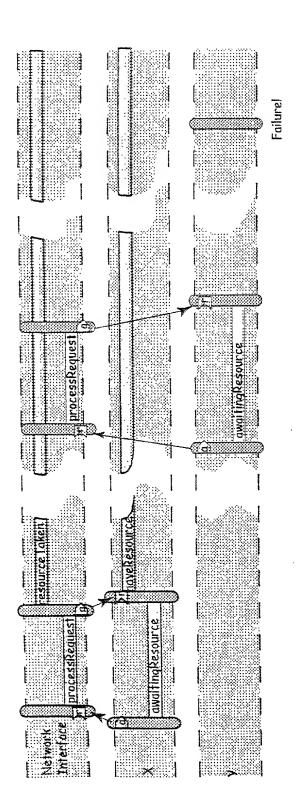


Figure 50

17 199

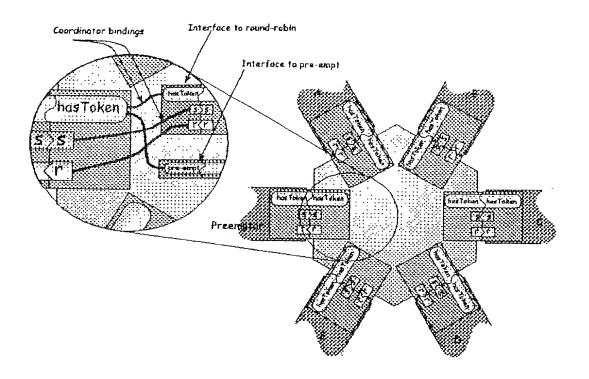


Figure 51A

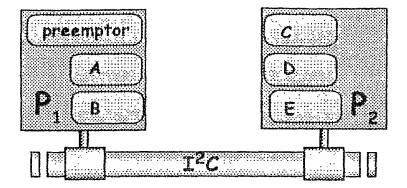
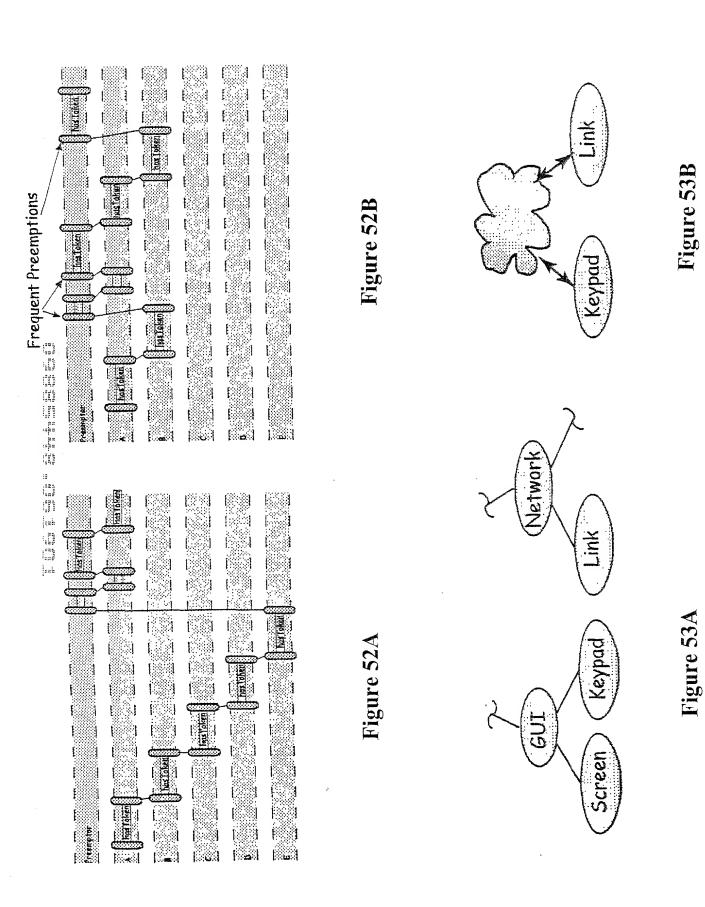


Figure 51B



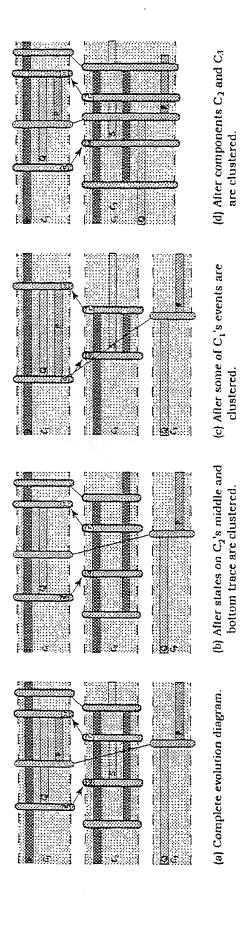


Figure 54

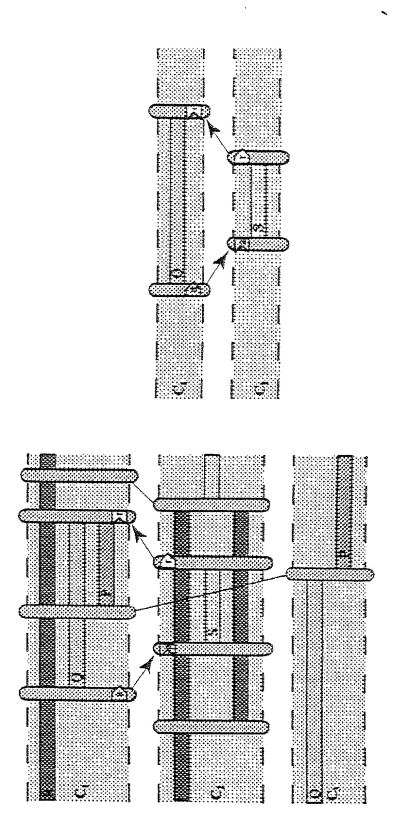


Figure 55A

Figure 55B

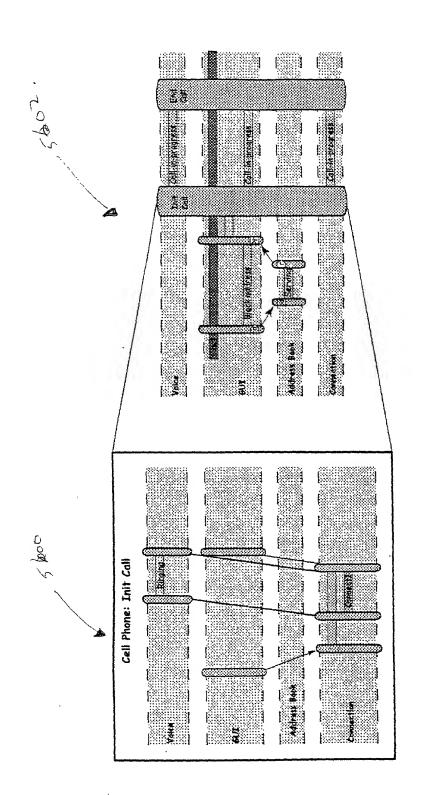


Figure 56

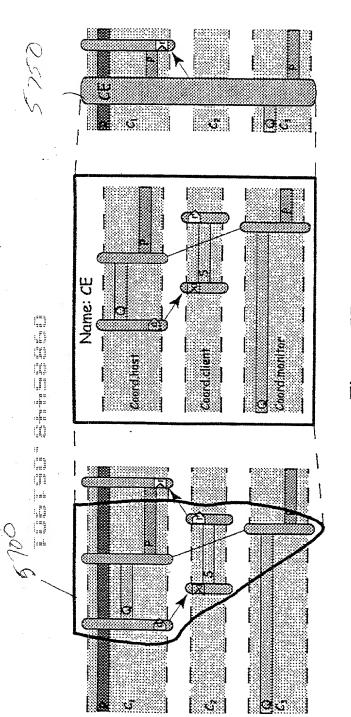
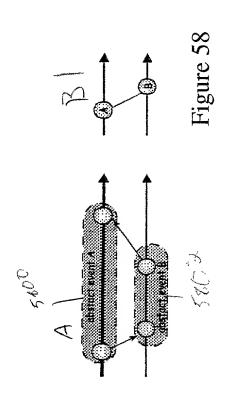


Figure 57



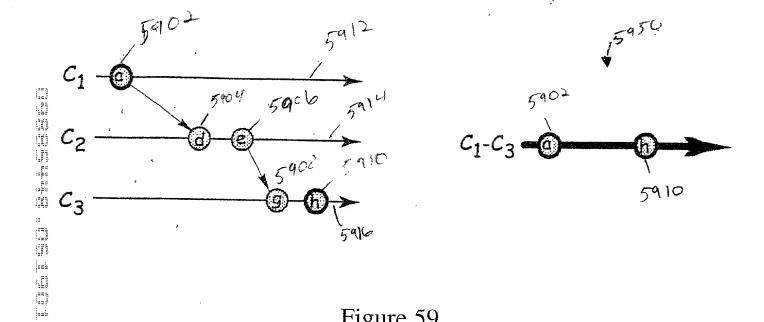


Figure 59

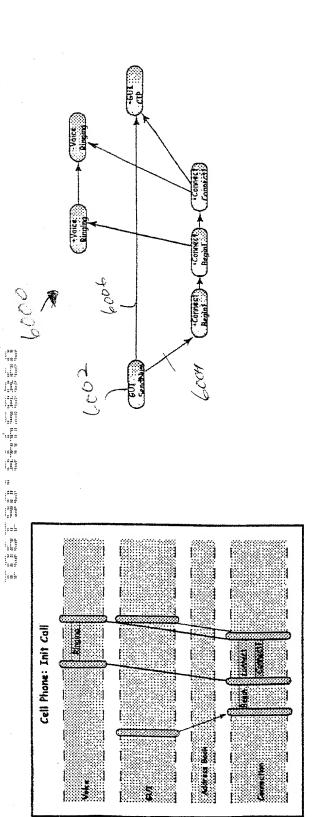


Figure 60

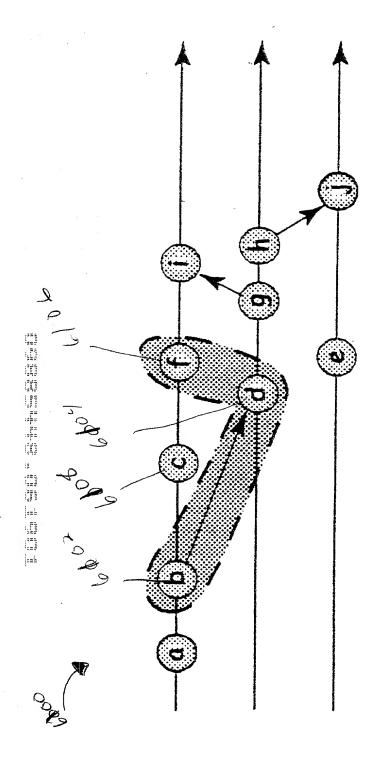


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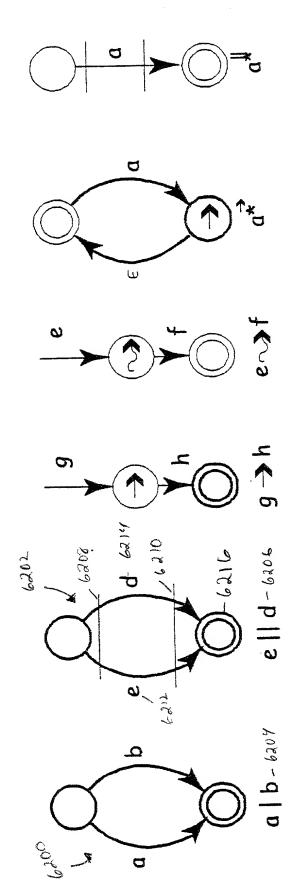


Figure 62

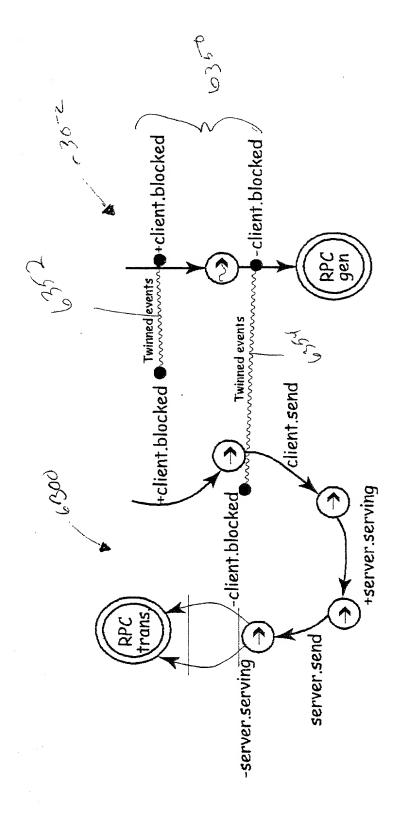
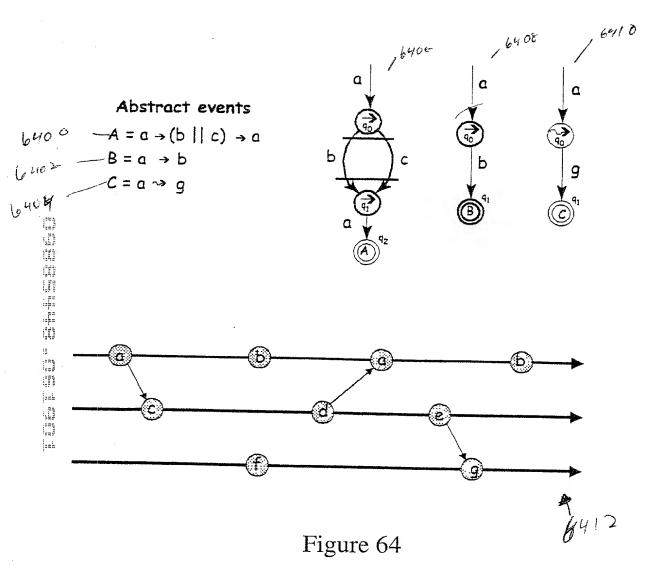


Figure 63



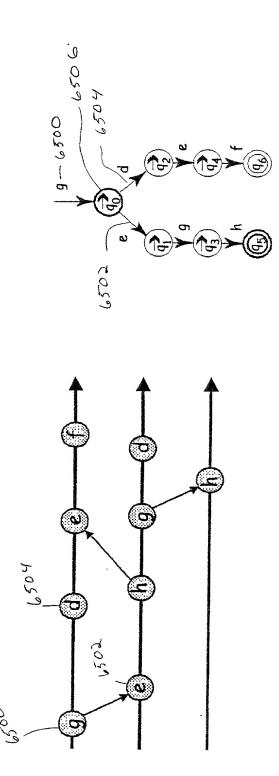


Figure 65

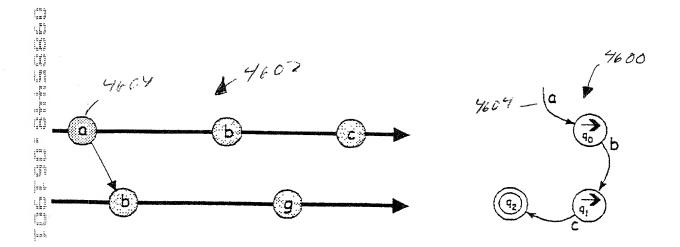


Figure 66